

A photograph of a walnut shell that has been cracked open. The two halves of the shell are visible, showing a light brown, textured exterior and a darker, smooth interior. A white rectangular card is placed inside the shell, partially visible between the two halves. The background is a plain, light color.

Matt Stabler
21 Sep 2010

Matt's PhD

- How we got here?
- Why are we here?
- Where are we?
- Where are we going?

How we got here?

- Graduated June 2006
 - 1st Class (hons) BSc Internet Computing @ Hull Uni
 - FYP: An investigation into a geo-spatial pervasive information gathering engine
- CF Consultant @ Protiviti Ltd
- Sept 2007
 - Paddy Nixon & Simon Dobson

IRCSET

- AutoSense: Gathering, Processing and Utilizing Context within an Automated System
 - AKA Mobile Construct
- 3 year Scholarship to Aug 2010
- Extended from Sep 2010 to ~Aug 2011

Structured PhD

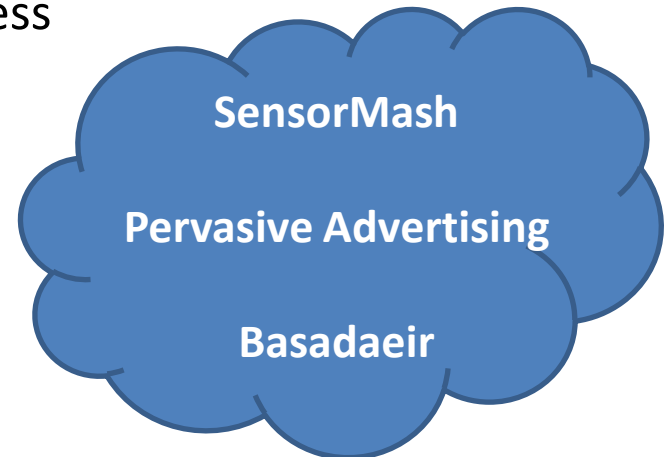
- Machine Learning
- Natural Computing
- *Core Research Skills (EMPS)*
- Distributed Systems
- *Innovation & Knowledge I*
- Agent-Oriented Software

RSS talk Dec 2008 and Transfer Apr 2009

(Exploiting human networks for delay tolerant environmental sensing)

Topic/Interest Timeline

- Sept 07
 - Autonomous Systems / Context Awareness
 - Pervasive Computing in general
- June 08
 - Wearable Computing
- Oct 08
 - Environmental sensing
- Jan 09
 - Sensor Nets and Delay Tolerant Networks (DTN)
- Mid 09
 - DTN
 - Human Interaction Networks
 - Social Networks
 - Human Mobility



Why are we here?

- Discovering things about people networks that we can't see
 - How are we connected?
 - Predictions about a social network
 - Future meetings
 - Communications opportunities

Interests

- Sensing Networks

Lindgren A, Mascolo C, Lonergan M, Mcconnell B. **Seal-2-Seal: A Delay-Tolerant Protocol for Contact Logging in Wildlife Monitoring Sensor Networks.**

- Small World

Travers J, Milgram S. **An experimental study of the small world problem.**

- Proximity networks

- Periodicity Hunting

Williamson, G., Cellai, D., Dobson, S., & Nixon, P. (2009). **Self-management of Routing on Human Proximity Networks.**

- What role does location have?

Stabeler, M., Cellai, D., Dobson, S., & Nixon, P. (2009). **Delay tolerant networks and spatially detailed human mobility.** In *Workshop on the Emergence of Delay-/Disruption-Tolerant Networks (E-DTN) in ICUMT*. St Petersburg.

http://mattstabeler.co.uk/publications/presentations/E-DTN_14Oct2009.pdf

Influencing Papers

- Zhang, Z. (2006). **Routing in intermittently connected mobile ad hoc networks and delay tolerant networks: overview and challenges.**
 - DTN state of the art
- Kossinets, G., Kleinberg, J., & Watts, D. (2008). **The structure of information pathways in a social communication network.**
 - Used vector clocks to derive statistics about networks
 - Sparked a lot of ideas about using vector clocks as a means to recording/sharing data amongst nodes
 - Related very well to GW & DC paper
- Song, C., Qu, Z., Blumm, N., & Barabási, A. (2010). **Limits of predictability in human mobility.**
 - Prediction of individual movement using a large dataset (coarse mobile phone locations)
- Numerous DTN algorithm papers – **CAR, BUBBLERap, Epidemic, Seal2Seal, ZebraNET**

Questions

- What is a node?
- How are edges defined?
- How do we **collect data** about mobility?
- How do we define what a location is?
- What can nodes **learn about the network**?
- How can nodes **communicate**?
- How do we deal with **privacy**? (not main focus)

Hypotheses?

- Human mobility patterns are predictable
- Human proximity patterns are predictable
- Knowledge of proximity ***and location*** makes opportunistic routing more efficient than proximity alone.
- There are low complexity algorithms based on vector clocks that can be used for routing
- Any given node will only need to communicate with other nodes **that they know**
 - *Most (?%) communications are to nodes within {x} hops locally, or {x++} hops globally*

Where are we now?

- Datasets
 - SocialSensing, GeoLife, CABSpotting, CenceMe(?)
- Simulator/Visualisation
 - Simple Playback
- Data analysis (WIP)
 - Co-location network
$$C_{AB}(t) = 1 - \theta(|x_A(t) - x_B(t)| - \lambda)$$
$$C_{AB} = \frac{1}{T} \sum C_{AB}(t)$$
 - $T = 1$ month, $t=1800s$, $\lambda = 200m$, Nodes = 156

Data set features

	GPS	WiFi	Bluetooth	Cell	Inferred Location	#Nodes
SocialSensing	☹️	😊	😊	😊	😊	😐
TomStalker	😐	😊	😊	😊	😊	☹️
Google Latitude	😊	☹️	☹️	☹️	😊	😊
GeoLife	😊	☹️	☹️	☹️	😊	😊
Reality Mining *	☹️	☹️	😊	😊	☹️	😊
Cab Spotting *+	😊	☹️	☹️	☹️	😊	😊

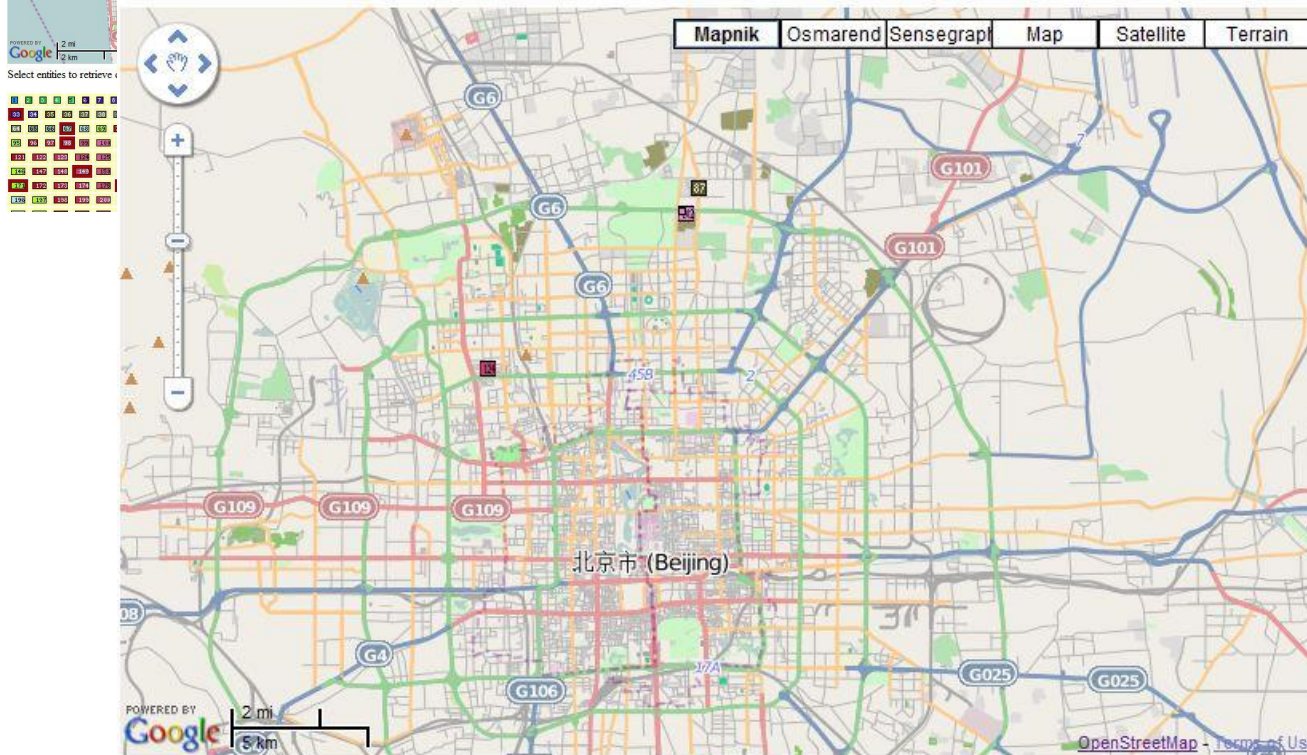
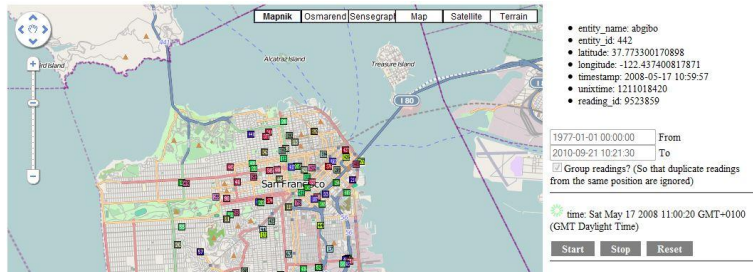
* Cited in literature

+ Not human movement

CABSpotting Dataset

Dataset Visualisation

GeoLife Dataset



Select entities to retrieve data for: **Toggle Selection**



- entity_name: user_0111
- entity_id: 102
- latitude: 40.022277832031
- longitude: 116.402709960938
- timestamp: 2007-04-01 00:54:39
- unixtime: 1175385302
- reading_id: 25080167
- log_type: log2
- source: 2007-04-01-GPS.log

1977-01-01 00:00:00 From
2010-09-21 10:25:22 To
☐ Group readings? (So that duplicate readings from the same position are ignored)

time: Sun Apr 01 2007 00:55:02 GMT+0100 (GMT Daylight Time)

Start Stop Reset

-50ms | -10ms | 50ms | +10 |
+50

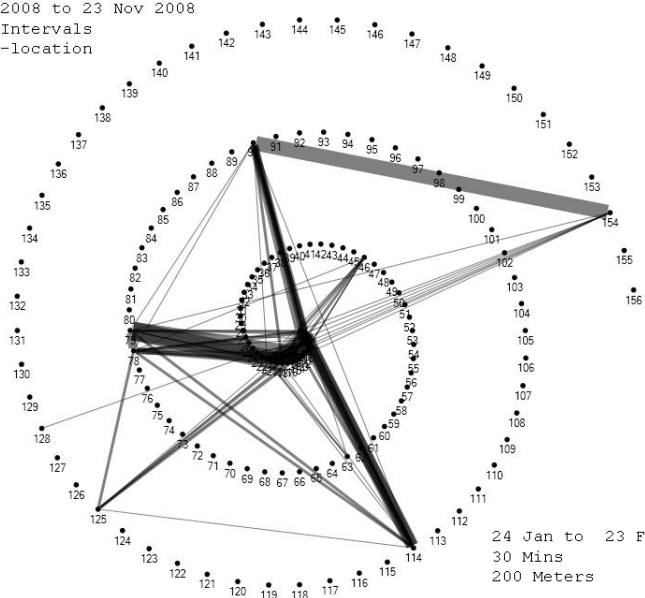
-10 | -1 | Tailsize: 10 | +1
+10

☒ Pan to marker? (moves map centre to most recent marker)

☐ Pre-load data? *not working*

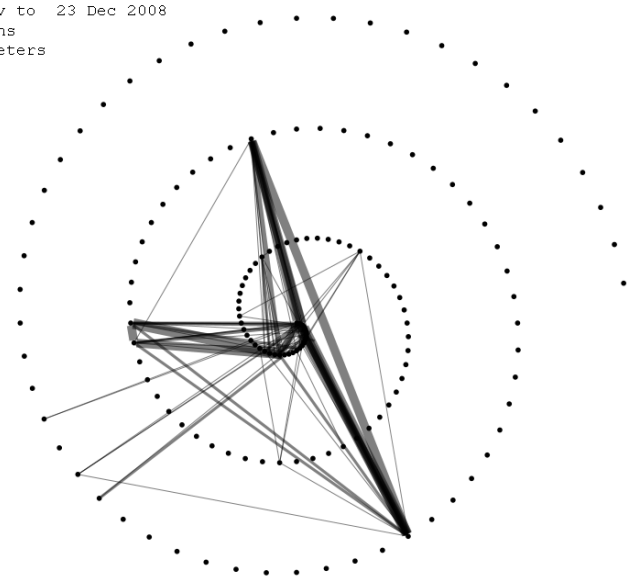
Loading entity list
HTTP Host: sensegraph.local
DB Host: localhost

23 Oct 2008 to 23 Nov 2008
 30 Min Intervals
 200m Co-location

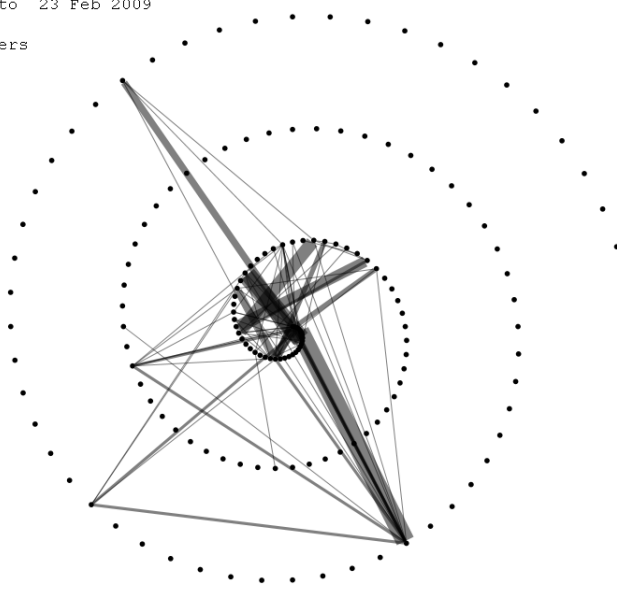


Initial Analysis

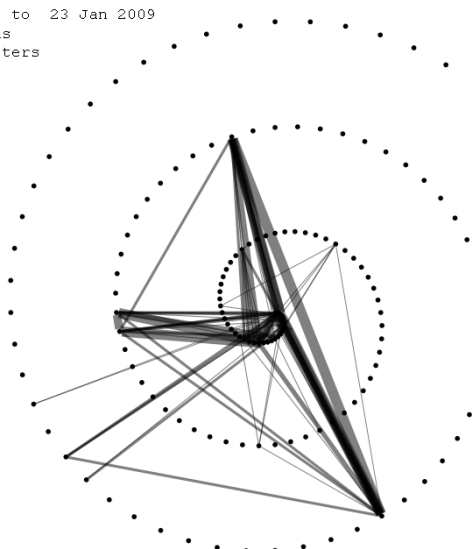
23 Nov to 23 Dec 2008
 30 Mins
 200 Meters



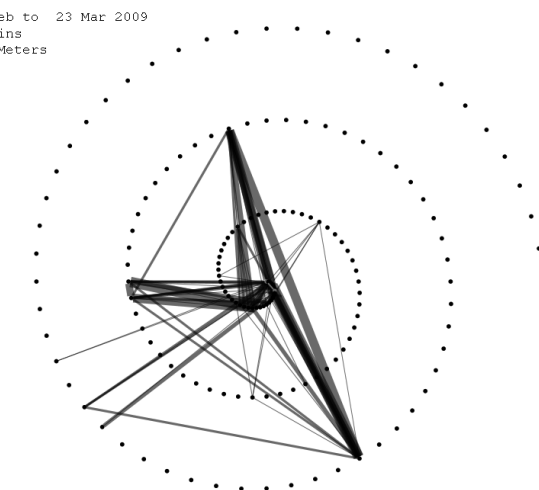
24 Jan to 23 Feb 2009
 30 Mins
 200 Meters



24 Dec to 23 Jan 2009
 30 Mins
 200 Meters



24 Feb to 23 Mar 2009
 30 Mins
 200 Meters



Co-locations in GeoLife dataset

$T = 1 \text{ month}$, $t = 1800s$, $\lambda = 200m$, Nodes = 156

Where are we going?

- Detection of local metrics
- Prediction of global structure
- Communication between nodes

Methods for detecting graph structure

- Measuring Periodicity

- Proximity
- Location

- Vector Clocks

- Range
- Update Rate
- Out-of-dateness

- ???

Prediction / Communication

- Predicting location
 - Markov Chains
 - Song et al Method
- Pairwise meta-data sharing
 - Sharing vector clock updates
 - Sharing location history/predictions
- Location based DTN algorithm
 - Predicting meetings
 - Predicting near-misses

Application

- P2P Over DTN
 - Sharing large syndicated content
- Recommendation
 - Are there social hubs (people) that make places good?
- Typical Scenarios (flawed)
 - Disaster Recovery (un-predictable)
 - Remote locations (there are better solutions)

What now?

- Plan for completion
 - Ideally ~ May 2011 ,
 - Hard ~ July/Aug 2011
- Experiment planning
- Paper targets
- Filling in the knowledge gaps

Where I keep my stuff

Meeting Notes etc.

[http://*guest:password*@mattstabeler.co.uk/phdblog/](http://guest:password@mattstabeler.co.uk/phdblog/)

Calendar

Google Calendar – mattstabeler@gmail.com

Papers and notes

Mendeley – matthew.stabeler@ucd.ie

Documents/Data

Google Docs – mattstabeler@gmail.com

Dropbox – matt@bigbadweb.co.uk

Publications, CV, etc.

mattstabeler.co.uk

Housekeeping

- Meeting Schedule
- Red-tape
- Demonstrating
 - Mo-Tu-We @ 9-10
 - We @ 2-4

