A photograph of a walnut shell split open, revealing the dark, textured nut inside. A white rectangular card is tucked into the left half of the shell. The card has the text "Matt's PhD" printed on it in a bold, black, sans-serif font.

Matt's PhD

Matt Stabeler
21 Sep 2010

- How we got here?
- Why are we here?
- Where are we?
- Where are we going?

How we got here?

- Graduated June 2006
 - 1st Class (hons) BSc Internet Computing @ Hull Uni
 - FYP: An investigation into a geo-spatial pervasive information gathering engine
- CF Consultant @ Protiviti Ltd
- Sept 2007
 - Paddy Nixon & Simon Dobson

IRCSET

- AutoSense: Gathering, Processing and Utilizing Context within an Automated System
 - AKA Mobile Construct
- 3 year Scholarship to Aug 2010
- Extended from Sep 2010 to ~Aug 2011

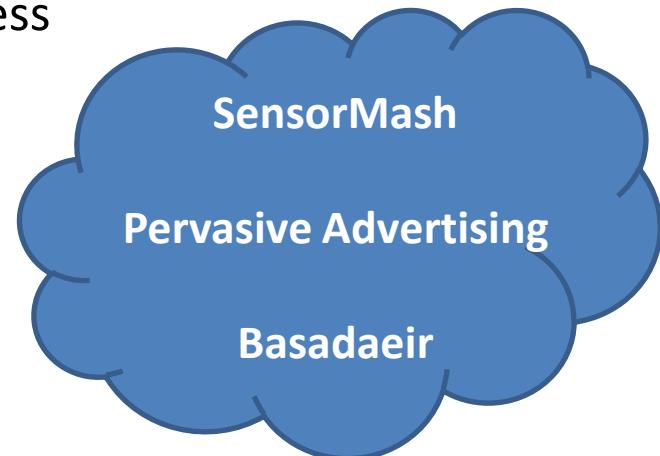
Structured PhD

- Machine Learning
- Natural Computing
- *Core Research Skills (EMPS)*
- Distributed Systems
- *Innovation & Knowledge I*
- Agent-Oriented Software

RSS talk Dec 2008 and Transfer Apr 2009
(Exploiting human networks for delay tolerant environmental sensing)

Topic/Interest Timeline

- Sept 07
 - Autonomous Systems / Context Awareness
 - Pervasive Computing in general
- June 08
 - Wearable Computing
- Oct 08
 - Environmental sensing
- Jan 09
 - Sensor Nets and Delay Tolerant Networks (DTN)
- Mid 09
 - DTN
 - Human Interaction Networks
 - Social Networks
 - Human Mobility



Why are we here?

- Discovering things about people networks that we can't see
 - How are we connected?
 - Predictions about a social network
 - Future meetings
 - Communications opportunities

Interests

- **Sensing Networks**

Lindgren A, Mascolo C, Lonergan M, McConnell B. **Seal-2-Seal: A Delay-Tolerant Protocol for Contact Logging in Wildlife Monitoring Sensor Networks.**

- **Small World**

Travers J, Milgram S. **An experimental study of the small world problem.**

- **Proximity networks**

- **Periodicity Hunting**

Williamson, G., Cellai, D., Dobson, S., & Nixon, P. (2009). **Self-management of Routing on Human Proximity Networks.**

- **What role does location have?**

Stabeler, M., Cellai, D., Dobson, S., & Nixon, P. (2009). **Delay tolerant networks and spatially detailed human mobility.** In *Workshop on the Emergence of Delay-/Disruption-Tolerant Networks (E-DTN) in ICUMT*. St Petersburg.

http://mattstabeler.co.uk/publications/presentations/E-DTN_14Oct2009.pdf

Influencing Papers

- Zhang, Z. (2006). **Routing in intermittently connected mobile ad hoc networks and delay tolerant networks: overview and challenges.**
 - DTN state of the art
- Kossinets, G., Kleinberg, J., & Watts, D. (2008). **The structure of information pathways in a social communication network.**
 - Used vector clocks to derive statistics about networks
 - Sparked a lot of ideas about using vector clocks as a means to recording/sharing data amongst nodes
 - Related very well to GW & DC paper
- Song, C., Qu, Z., Blumm, N., & Barabási, A. (2010). **Limits of predictability in human mobility.**
 - Prediction of individual movement using a large dataset (coarse mobile phone locations)
- Numerous DTN algorithm papers – **CAR, BUBBLERap, Epidemic, Seal2Seal, ZebraNET**

Questions

- What is a node?
- How are edges defined?
- How do we **collect data** about mobility?
- How do we define what a location is?
- What can nodes **learn about the network**?
- How can nodes **communicate**?
- How do we deal with **privacy**? (not main focus)

Hypotheses?

- Human mobility patterns are predictable
- Human proximity patterns are predictable
- Knowledge of proximity ***and location*** makes opportunistic routing more efficient than proximity alone.
- There are low complexity algorithms based on vector clocks that can be used for routing
- Any given node will only need to communicate with other nodes **that they know**
 - *Most (?) communications are to nodes within {x} hops locally, or {x++} hops globally*

Where are we now?

- Datasets
 - SocialSensing, GeoLife, CABSpotting, CenceMe(?)
- Simulator/Visualisation
 - Simple Playback
- Data analysis (WIP)
 - Co-location network
$$C_{AB}(t) = 1 - \theta(|x_A(t) - x_B(t)| - \lambda)$$
$$C_{AB} = \frac{1}{T} \sum C_{AB}(t)$$
 - $T = 1$ month, $t=1800s$, $\lambda = 200m$, Nodes = 156

Data set features

	GPS	WiFi	Bluetooth	Cell	Inferred Location	#Nodes
SocialSensing	😢	😊	😊	😊	😊	😐
TomStalker	😐	😊	😊	😊	😊	😢
Google Latitude	😊	😢	😢	😢	😊	😊
GeoLife	😊	😢	😢	😢	😊	😊
Reality Mining *	😢	😢	😊	😊	😢	😊
Cab Spotting *+	😊	😢	😢	😢	😊	😊

* Cited in literature

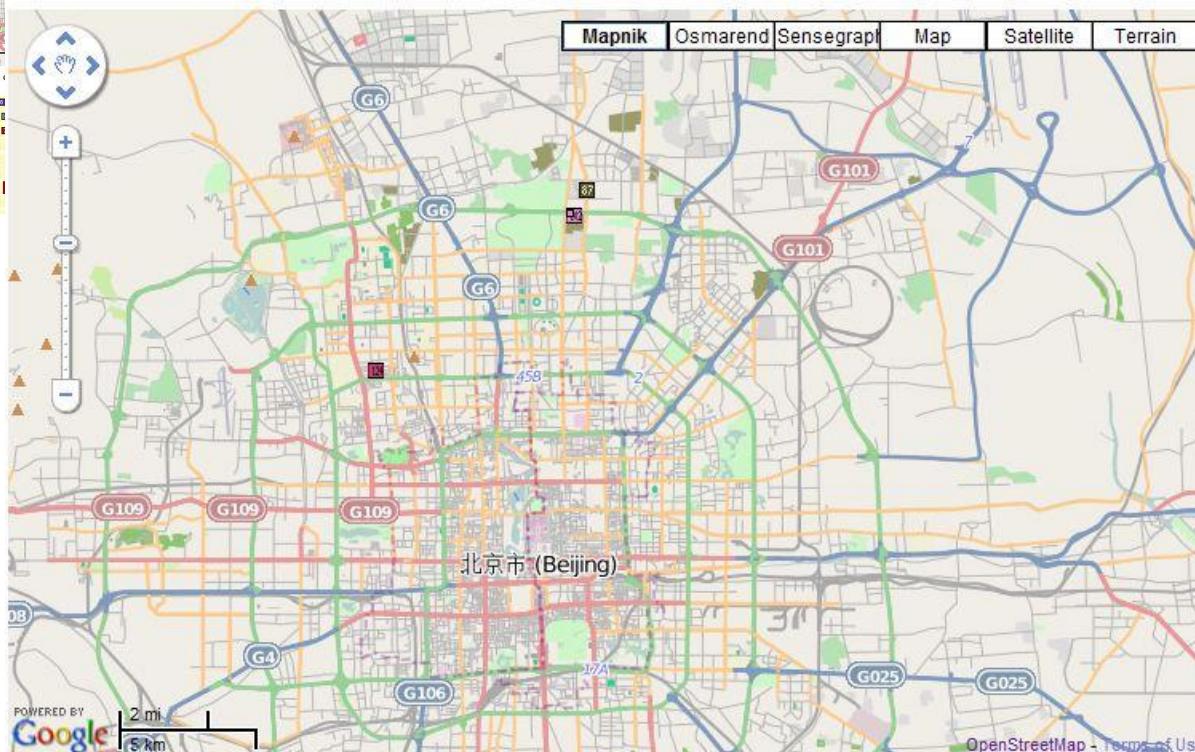
+ Not human movement

CABSpotting Dataset



Dataset Visualisation

GeoLife Dataset



- entity_name: user_0111
- entity_id: 102
- latitude: 40.022277832031
- longitude: 116.402709960938
- timestamp: 2007-04-01 00:54:39
- unixtime: 1175385302
- reading_id: 25080167
- log_type: log2
- source: 2007-04-01-GPS.log

1977-01-01 00:00:00 From
2010-09-21 10:25:22 To
 Group readings? (So that duplicate readings from the same position are ignored)

time: Sun Apr 01 2007 00:55:02 GMT+0100 (GMT Daylight Time)

Start **Stop** **Reset**

-50ms | -10ms | 50ms | +10 |
+50

-10 | -1 | Tailsize: 10 | +1
+10

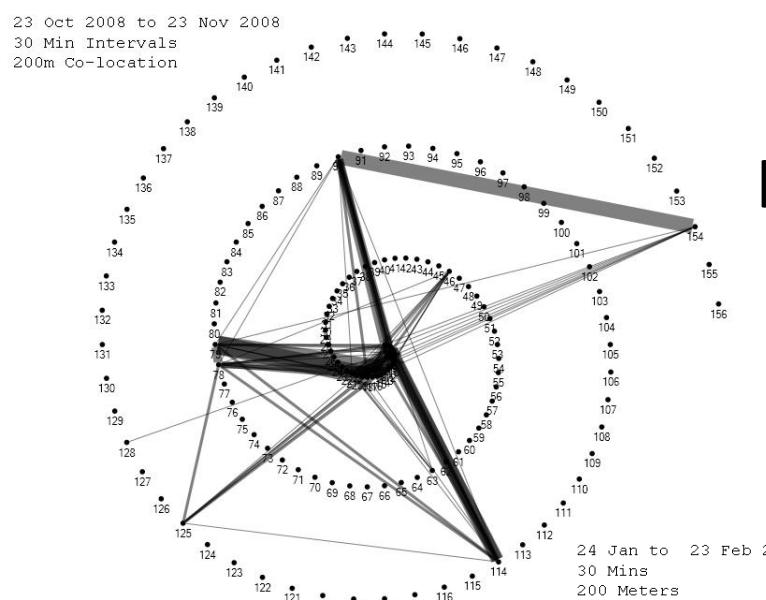
Pan to marker? (moves map centre to most recent marker)

Pre-load data? *not working*

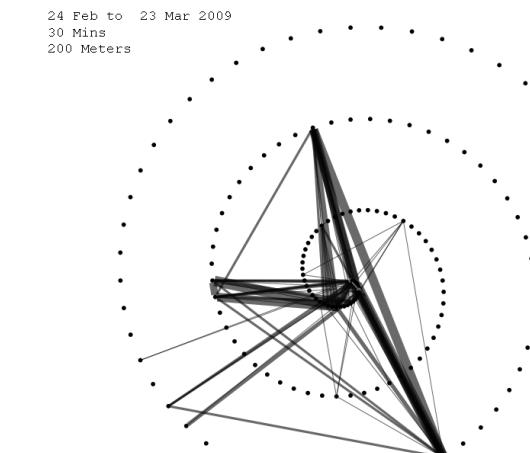
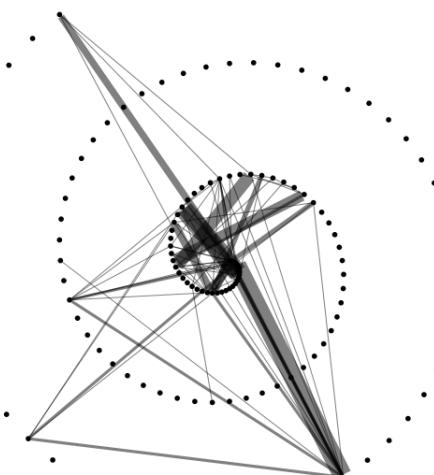
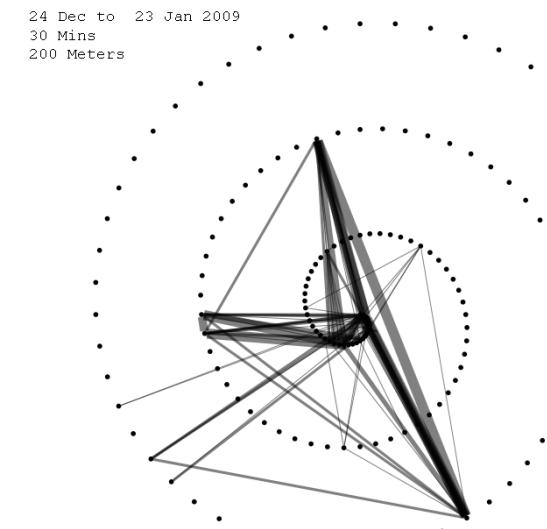
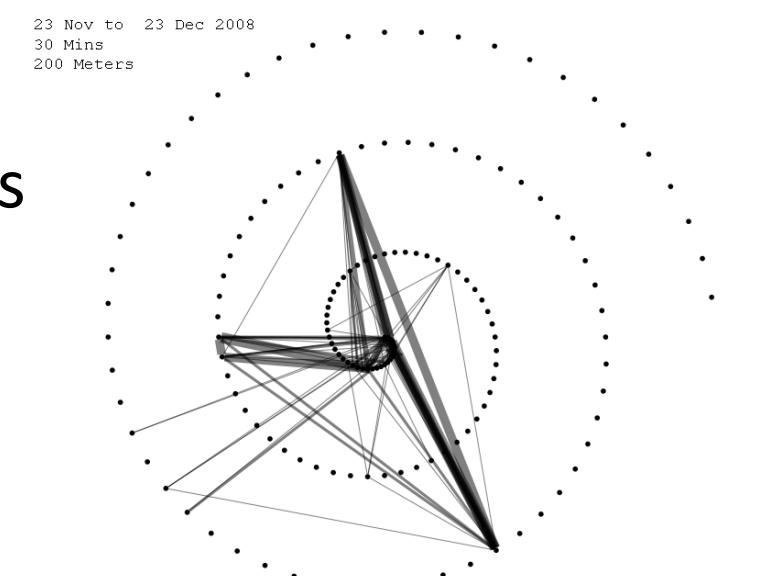
Loading entity list
HTTP Host: sensegraph.local
DB Host: localhost

Select entities to retrieve data for: **Toggle Selection**

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31	32																														
33	34	35	36	37	38	39	40	41	42	43	44	45	46	47	48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63																															
64	65	66	67	68	69	70	71	72	73	74	75	76	77	78	79	80	81	82	83	84	85	86	87	88	89	90	91	92	93	94																															
95	96	97	98	99	100	101	102	103	104	105	106	107	108	109	110	111	112	113	114	115	116	117	118	119	120	121	122	123	124	125	126	127	128	129	130	131	132	133	134	135	136	137	138	139	140	141	142	143	144	145	146	147	148	149	150	151	152	153	154	155	156



Initial Analysis



Co-locations in GeoLife dataset
 $T = 1$ month, $t = 1800s$, $\lambda = 200m$, Nodes = 156

Where are we going?

- Detection of local metrics
- Prediction of global structure
- Communication between nodes

Methods for detecting graph structure

- Measuring Periodicity
 - Proximity
 - Location
- Vector Clocks
 - Range
 - Update Rate
 - Out-of-dateness
- ???

Prediction / Communication

- Predicting location
 - Markov Chains
 - Song et al Method
- Pairwise meta-data sharing
 - Sharing vector clock updates
 - Sharing location history/predictions
- Location based DTN algorithm
 - Predicting meetings
 - Predicting near-misses

Application

- P2P Over DTN
 - Sharing large syndicated content
- Recommendation
 - Are there social hubs (people) that make places good?
- Typical Scenarios (flawed)
 - Disaster Recovery (un-predictable)
 - Remote locations (there are better solutions)

What now?

- Plan for completion
 - Ideally ~ May 2011 ,
 - Hard ~ July/Aug 2011
- Experiment planning
- Paper targets
- Filling in the knowledge gaps

Where I keep my stuff

Meeting Notes etc.

<http://guest:password@mattstabeler.co.uk/phdblog/>

Calendar

Google Calendar – mattstabeler@gmail.com

Papers and notes

Mendeley – matthew.stabeler@ucd.ie

Documents/Data

Google Docs – mattstabeler@gmail.com

Dropbox – matt@bigbadweb.co.uk

Publications, CV, etc.

mattstabeler.co.uk

Housekeeping

- Meeting Schedule
- Red-tape
- Demonstrating
 - Mo-Tu-We @ 9-10
 - We @ 2-4

